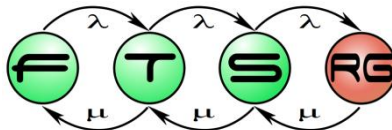


# Extensions to the CEGAR Approach on Petri Nets

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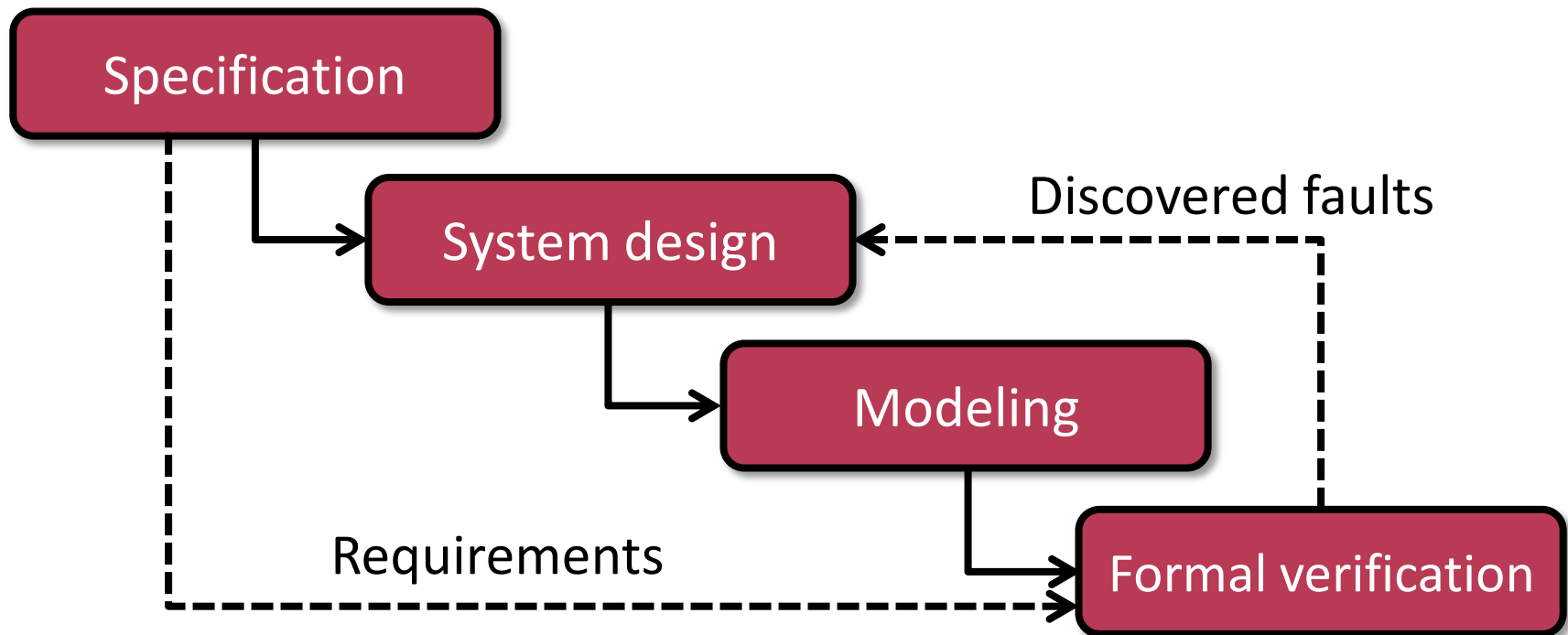


# Outline of the talk

1. Introduction
2. CEGAR approach on Petri nets
3. Theoretical results
4. Algorithmic contributions
5. Evaluation
6. Conclusion

# Introduction – Formal methods

- Complex, distributed, safety-critical systems
  - Suitability and faultlessness is important
  - Mathematically precise verification is required
  - Formal modeling and analysis can provide such tools



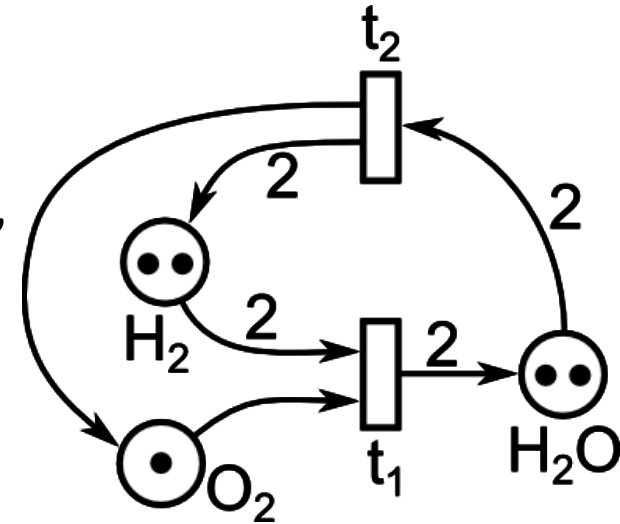
# Introduction – Petri nets

## ■ Petri nets

- Widely used modeling formalism
- Asynchronous, distributed, parallel, non-deterministic systems

## ■ Structure

- Bipartite graph
  - Places, transitions, weighted arcs, tokens



## ■ Dynamic behavior

- State: distribution of tokens (marking)
- Firing of a transition: consumes and produces tokens

# Introduction – Reachability analysis

## ■ Reachability analysis

- Formal verification technique
- Checks, if a given state is reachable from the initial state
- Drawback: complexity

## ■ Complexity

- State space can be large or infinite
- Reachability is decidable, but at least EXPSPACE-hard
- A possible solution is to use abstraction

# CEGAR approach

- **C**ounter**E**xample **G**uided **A**bstraction **R**efinement
  - General approach
    - Can handle large or infinite state space
  - Works on an abstraction of the original model
    - Less detailed state space
    - Finite, smaller representation
  - Abstraction refinement is required
    - An action in the abstract model may not be realizable in the original model
    - Refine the abstraction using the information from the explored part of the state space

# CEGAR approach on Petri nets

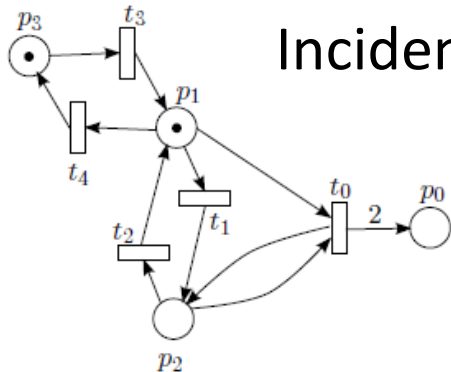
- Abstraction of Petri nets: state equation

Initial state

$$m_0 + Cx = m_1$$

Target state

Incidence matrix



$$\begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ -1 & -1 & 1 & 1 & -1 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 1 \end{bmatrix}$$

Firing count  
of transitions  
(*unknown*)

State  
equation

Initial  
abstraction

Reachability  
problem

# CEGAR approach on Petri nets

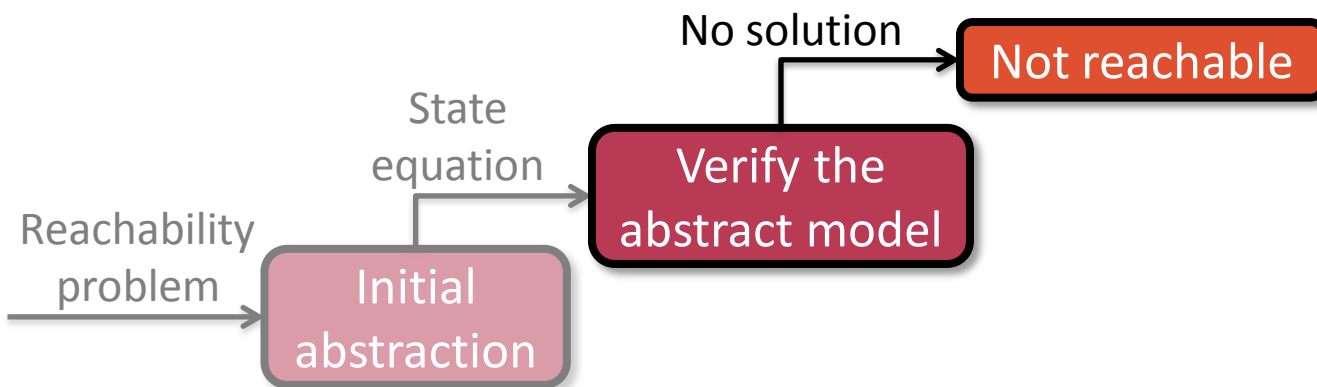
## ■ Verification of the abstract model

- Solving the state equation for the firing count of transitions

$$m_0 + C\mathbf{x} = m_1$$

- Integer Linear Programming problem

- Necessary, but not sufficient criterion for reachability

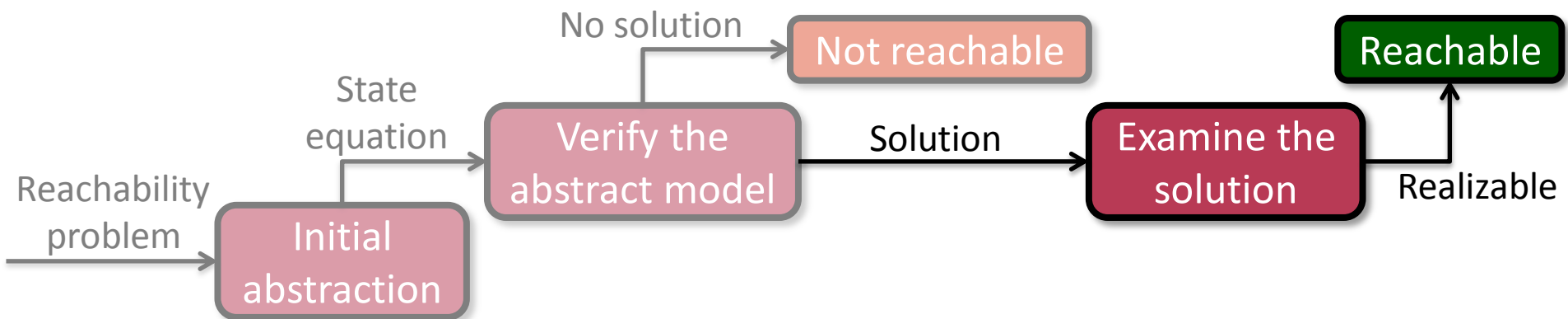
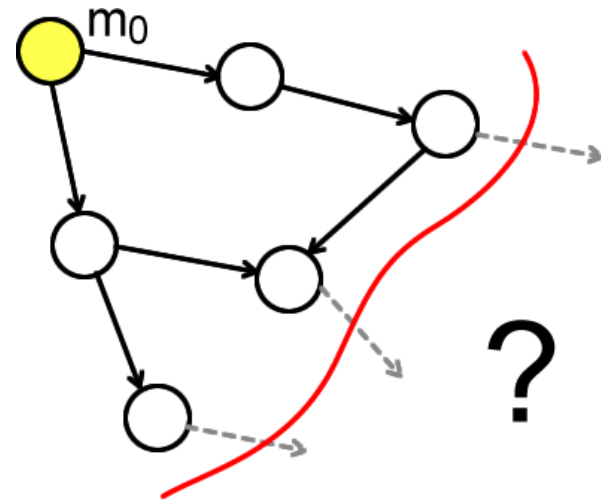
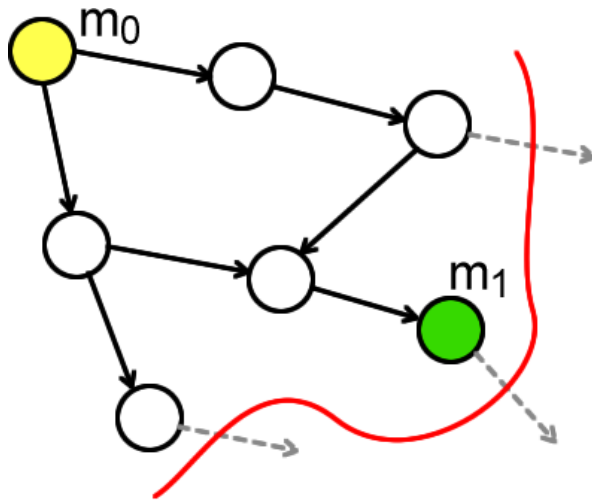




# CEGAR approach on Petri nets

- Examining the solution

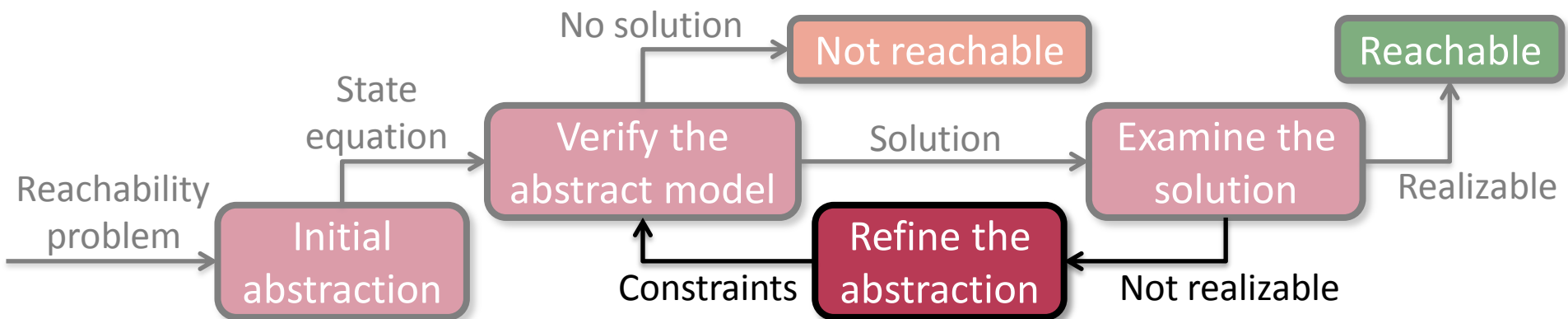
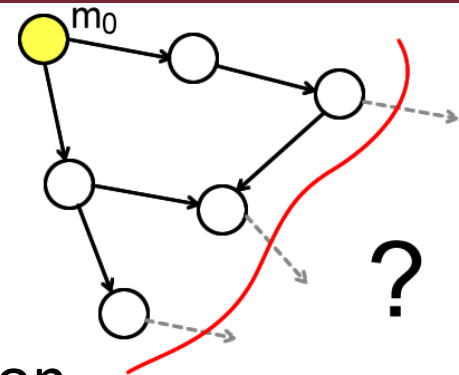
- Bounded exploration of the state space



# CEGAR approach on Petri nets

## ■ Abstraction refinement

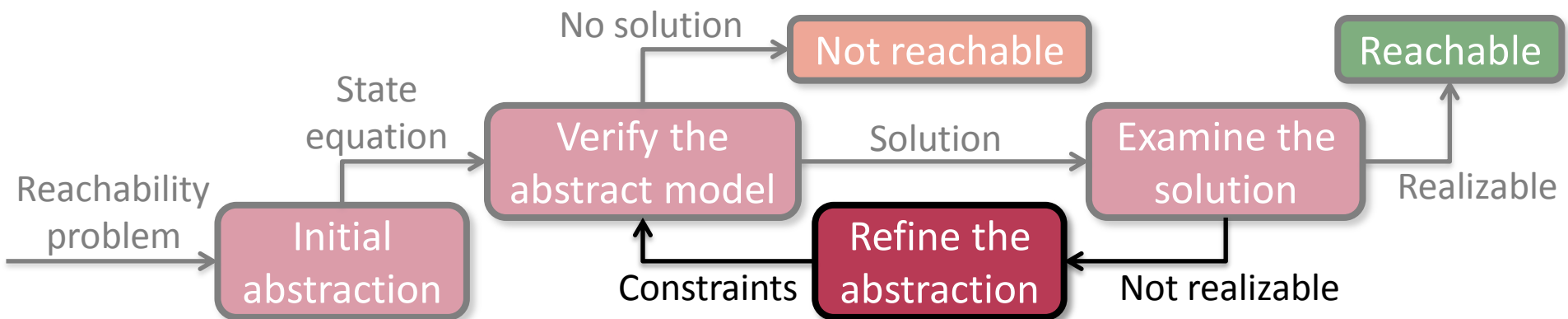
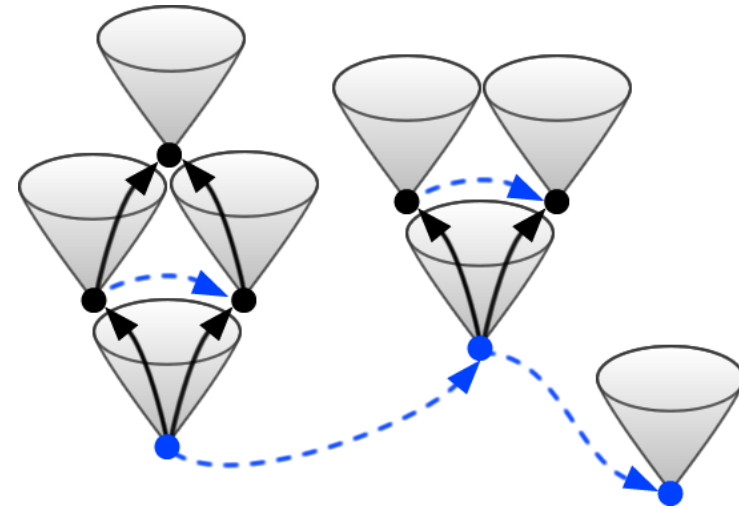
- Exclude the counterexample without losing any realizable solution
- Constraints can be added to the state equation
  - The state equation may become infeasible
  - A new solution can be obtained
- Traversing the solution space instead of the state space



# CEGAR approach on Petri nets

## ■ Traversing the solution space

- Base vector + linear combination of invariants
- Constraint types:
  - Jump: obtain another base vector
  - Increment: obtain non-minimal solutions

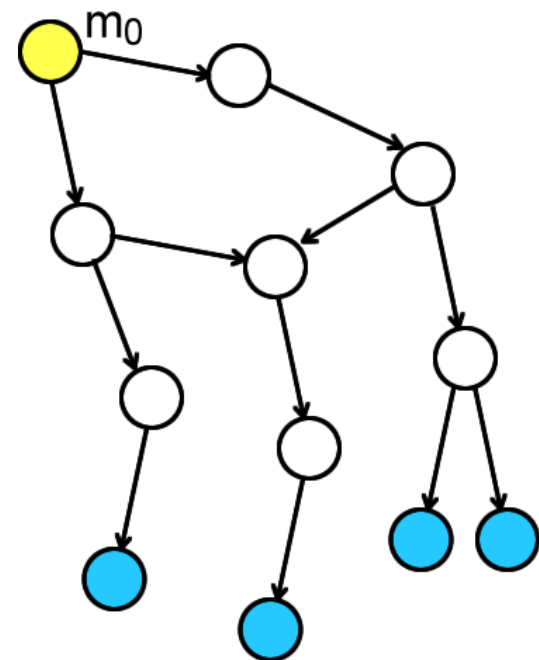


# Our work

- Examination of the algorithm
  - **Correctness**
  - Completeness
- Improving the algorithm
  - Extending the set of decidable problems
  - New criterion for termination
- Extending the algorithm
  - Solving submarking coverability
  - Handling inhibitor arcs

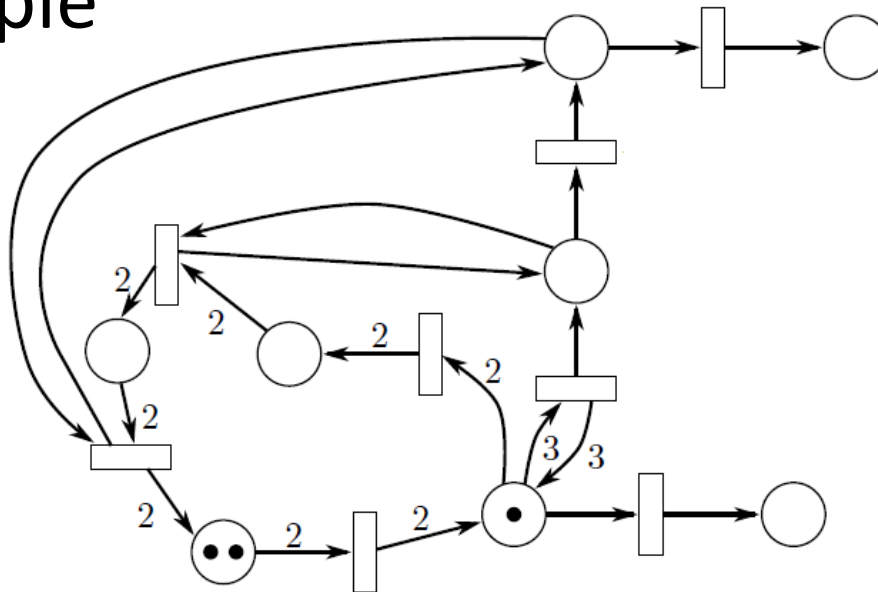
# Correctness of the algorithm

- The CEGAR method is proved to be correct, but:
- A heuristic is used to calculate the constraints
  - Uses only information from maximal firing sequences
    - This information may not be enough
  - The algorithm may over-estimate the constraints
    - ... and give an incorrect answer



# Correctness of the algorithm

- We proved the incorrectness of the heuristic by a counterexample



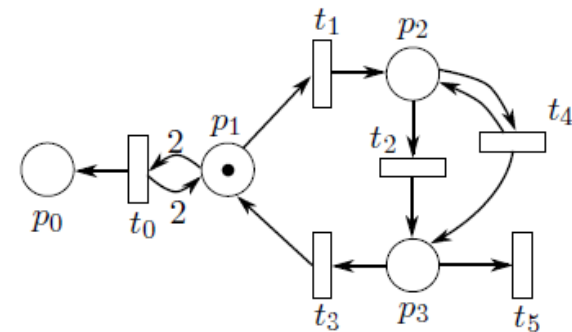
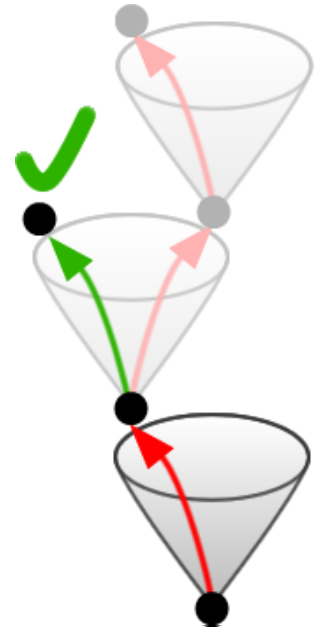
- In our improved algorithm:
  - We use the information of intermediate states
  - Detect the over-estimation and do not give an incorrect answer

# Our work

- Examination of the algorithm
  - Correctness
  - **Completeness**
- Improving the algorithm
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# Completeness of the algorithm

- The algorithm is incomplete due to its iteration strategy
  - An invariant is added to the solution which can be fired, but does not help
    - The same states are reached  
→ the same invariant is added again
  - This solution is skipped to avoid non-termination
    - In some cases using another invariant would help
  - We proved this by counterexamples





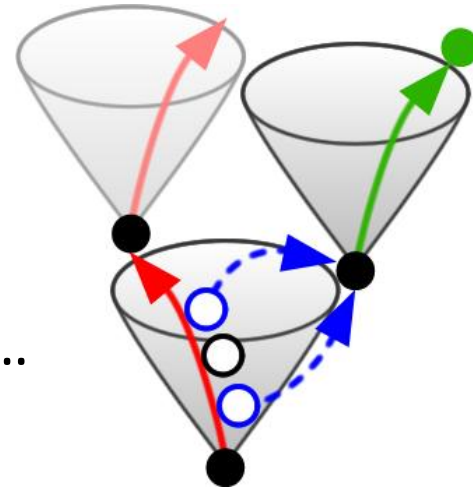
# Our work

- Examination of the algorithm
  - Correctness
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- Improving the algorithm
  - **Extending the set of decidable problems**
  - New criterion for termination
- Extending the algorithm
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# Algorithmic contributions - Improvements

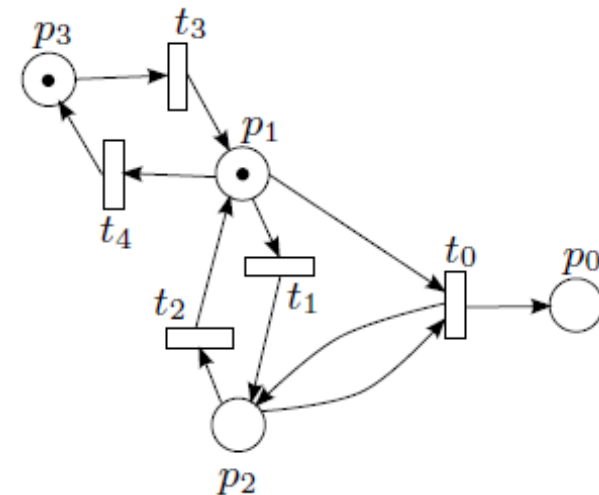
## ■ When a solution is skipped...

- ...the algorithm checks if any intermediate state can lead to a realizable solution
- Not all important states are recognized, due to ...
  - ... the ordering of the states
  - ... optimizations



## ■ We defined a total ordering on the intermediate states

- Every state closer to a realizable solution is recognized
- → Extends the set of decidable problems

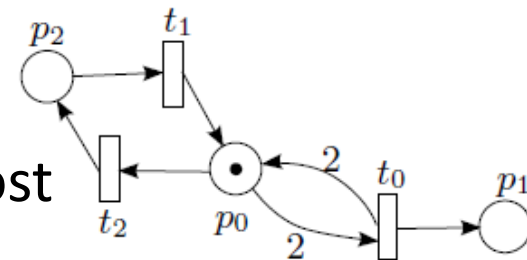


# Our work

- Examination of the algorithm
  - Correctness
  - Completeness
- Improving the algorithm
  - Extending the set of decidable problems
  - **New criterion for termination**
- Extending the algorithm
  - Solving submarking coverability
  - Handling inhibitor arcs

# Algorithmic contributions - Improvements

- We developed a new termination criterion
  - Before applying a constraint, a modified form of the state equation is checked
  - Constraints that cannot help, can be detected before applying them
- Advantages
  - Cuts the search space efficiently
  - Can prevent non-termination
    - We proved that no realizable solution is lost
    - → Extends the set of decidable problems



# Our work

- Examination of the algorithm
  - Correctness
  - Completeness
- Improving the algorithm
  - Extending the set of decidable problems
  - New criterion for termination
- Extending the algorithm
  - **Solving submarking coverability**
  - Handling inhibitor arcs

# Algorithmic contributions - Extensions

- Submarking coverability problem
  - Linear conditions are given (instead of the target state)
  - Checks, if a state can be reached, for which the given conditions hold
- Solving submarking coverability using CEGAR
  - We transformed the conditions on the state to conditions on transitions  $\rightarrow$  ILP problem
- New types of problems can be analyzed
  - Analysis of subsystems
  - Reachability of infinite set of states

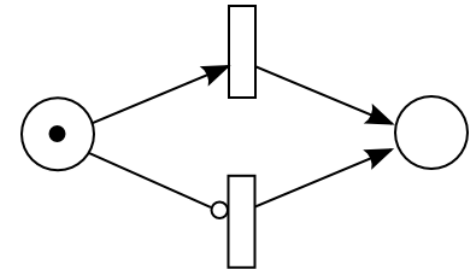
# Our work

- Examination of the algorithm
  - Correctness
  - Completeness
- Improving the algorithm
  - Extending the set of decidable problems
  - New criterion for termination
- Extending the algorithm
  - Solving submarking coverability
  - **Handling inhibitor arcs**

# Algorithmic contributions - Extensions

## ■ Inhibitor arcs

- Petri nets extended with inhibitor arcs are Turing complete
- The reachability problem in general is undecidable



## ■ Handling inhibitor arcs in the CEGAR approach

- We introduced new types of constraints
- We extended the total ordering on intermediate states
- Completeness cannot be guaranteed, but we tested the algorithm on several Petri nets



# Evaluation

# Evaluation

- We implemented our algorithm
  - PetriDotNet framework
    - Modeling and analysis of Petri nets
    - Supports add-ins
- We compared our algorithm to...
  - ... the original implementation
    - SARA tool
    - Won several categories at the model checking contest 2013
  - ... the saturation algorithm
    - Other type of reachability analysis method
    - Implemented in the PetriDotNet framework



# Evaluation

For certain models, the algorithmic contributions reduce the computational effort and **our algorithm can solve problems that SARA cannot**

Model	SARA tool	Our algorithm
CP_NR 10	0,2 s	0,5 s
CP_NR 25	111 s	2 s
CP_NR 50	TO	16 s
Kanban 1000	0,2 s	1 s
FMS 1500	0,5 s	5 s
MAPK	0,2 s	1 s

Constant speed penalty due to the managed environment and the overhead of the algorithmic contributions

The ILP solver can produce results efficiently

Model	Saturation	Our algorithm
Kanban 1000	TO	1 s
FMS 1500	TO	5 s
SlottedRing 50	4 s	433 s
Dphil 50	0,5 s	45 s

Solving the ILP problem dominates run-time

TO: Time out (runtime > 600 s)

# Conclusion

- Theoretical results
  - The iteration strategy of the CEGAR approach is incomplete
  - A heuristic in the original algorithm is incorrect
    - We detect such situations
- Algorithmic contributions
  - Extend the set of decidable problems
  - Reduce the search space
  - Solve new classes of problems
    - Submarking coverability
    - Petri nets with inhibitor arcs

# Thank you for your attention!

Questions?